

satisfying the data monster with fewer resources

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/nnovationsfonden

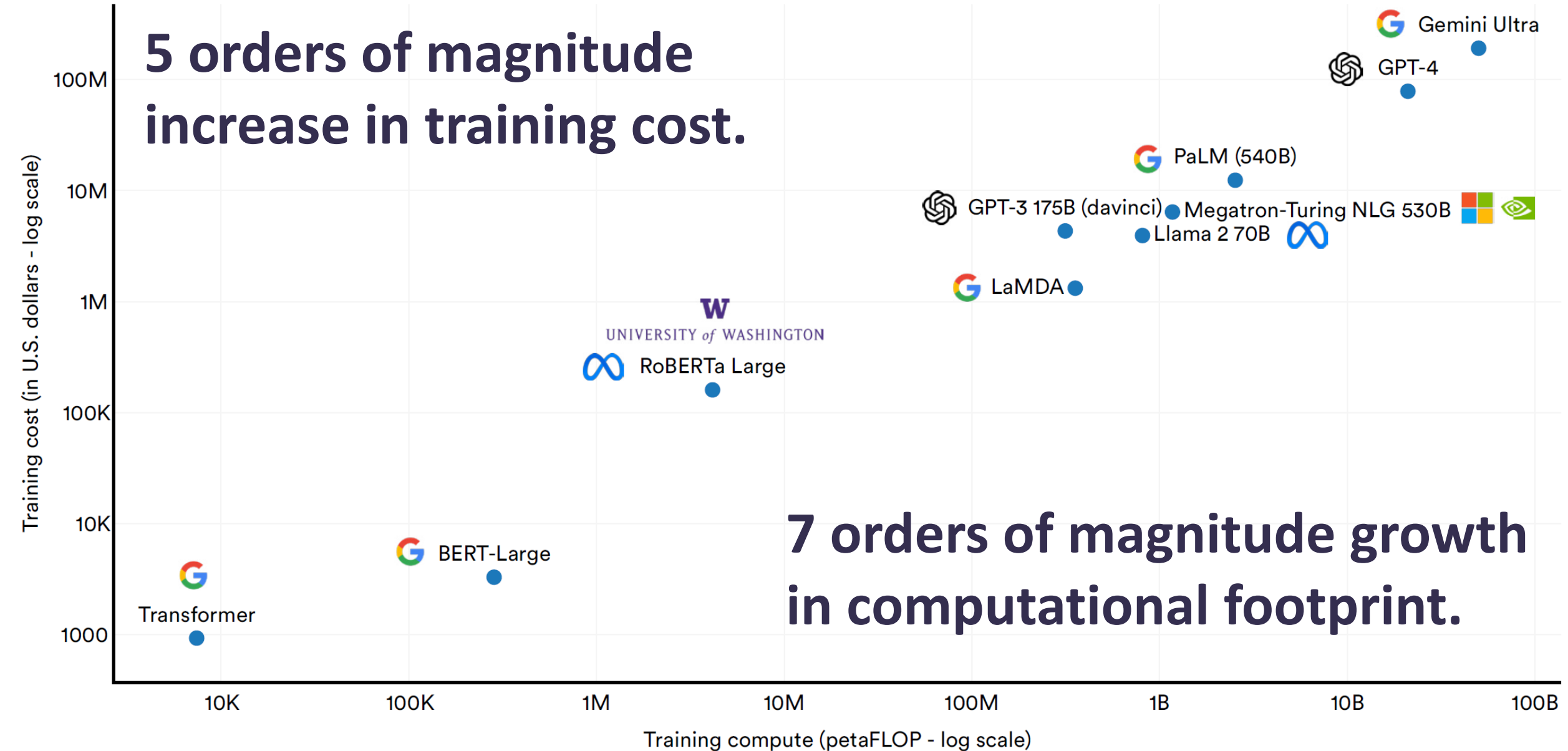


novo nordisk
foundation

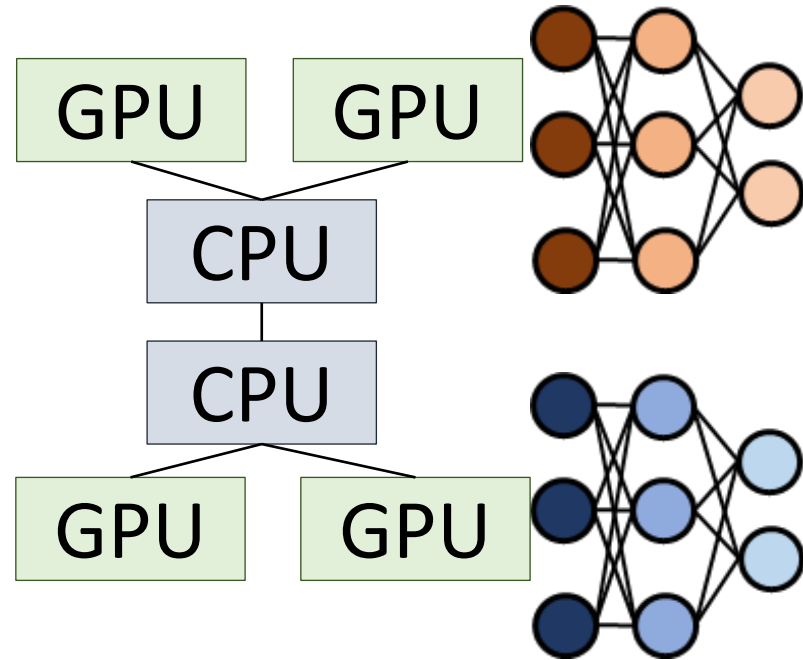
language model training (2017 – today)

**5 orders of magnitude
increase in training cost.**

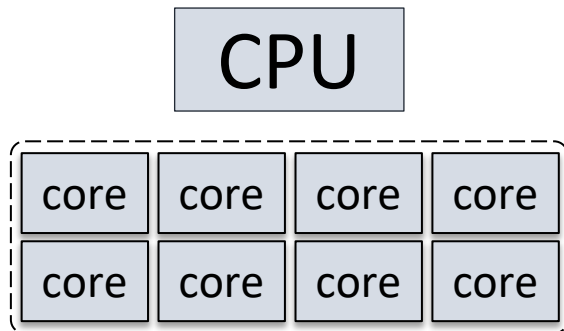
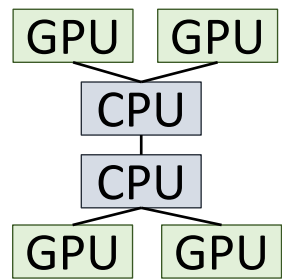
**7 orders of magnitude growth
in computational footprint.**



deep learning hardware



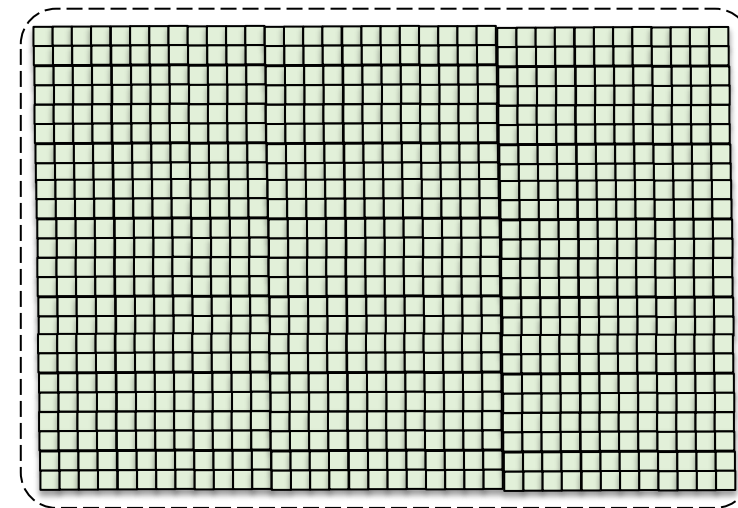
deep learning commodity hardware



central processing unit

- ➔ several (complex) cores
- ➔ good for latency-oriented tasks & single-core performance
 - throughput- vs latency-oriented designs exist among CPUs as well

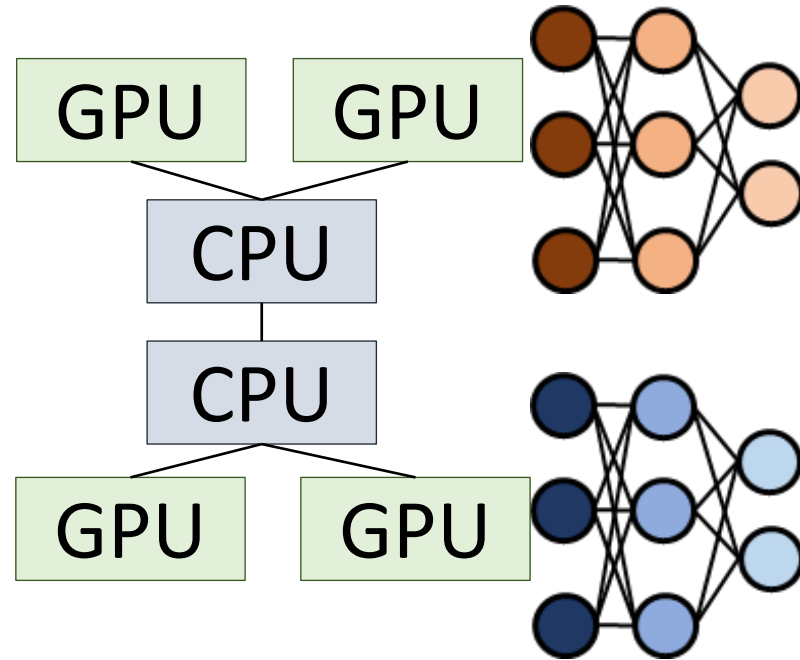
GPU



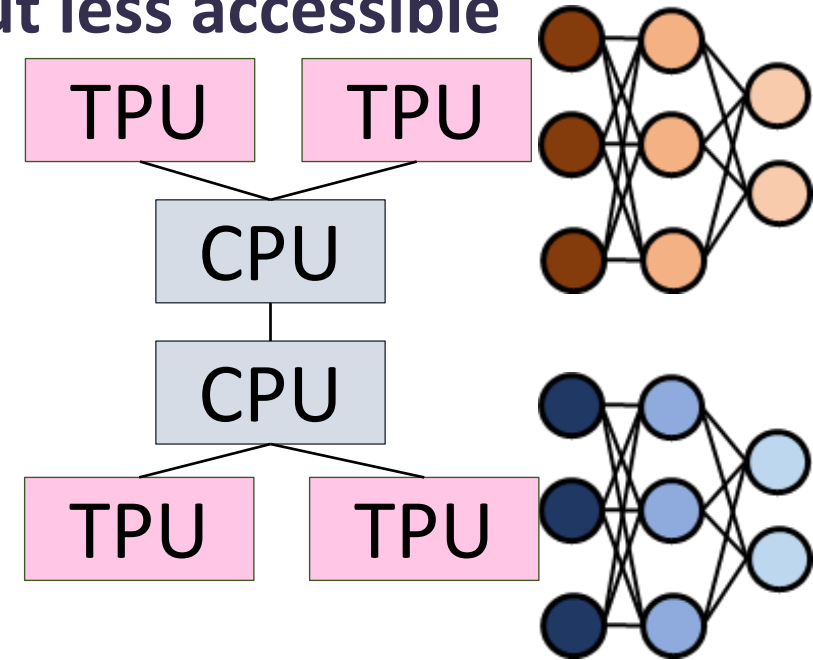
graphics processing unit

- ➔ many (simple) cores
- ➔ good for throughput-oriented & embarrassingly parallel tasks
 - ➔ good for deep learning
 - e.g., large matrix operations

deep learning hardware

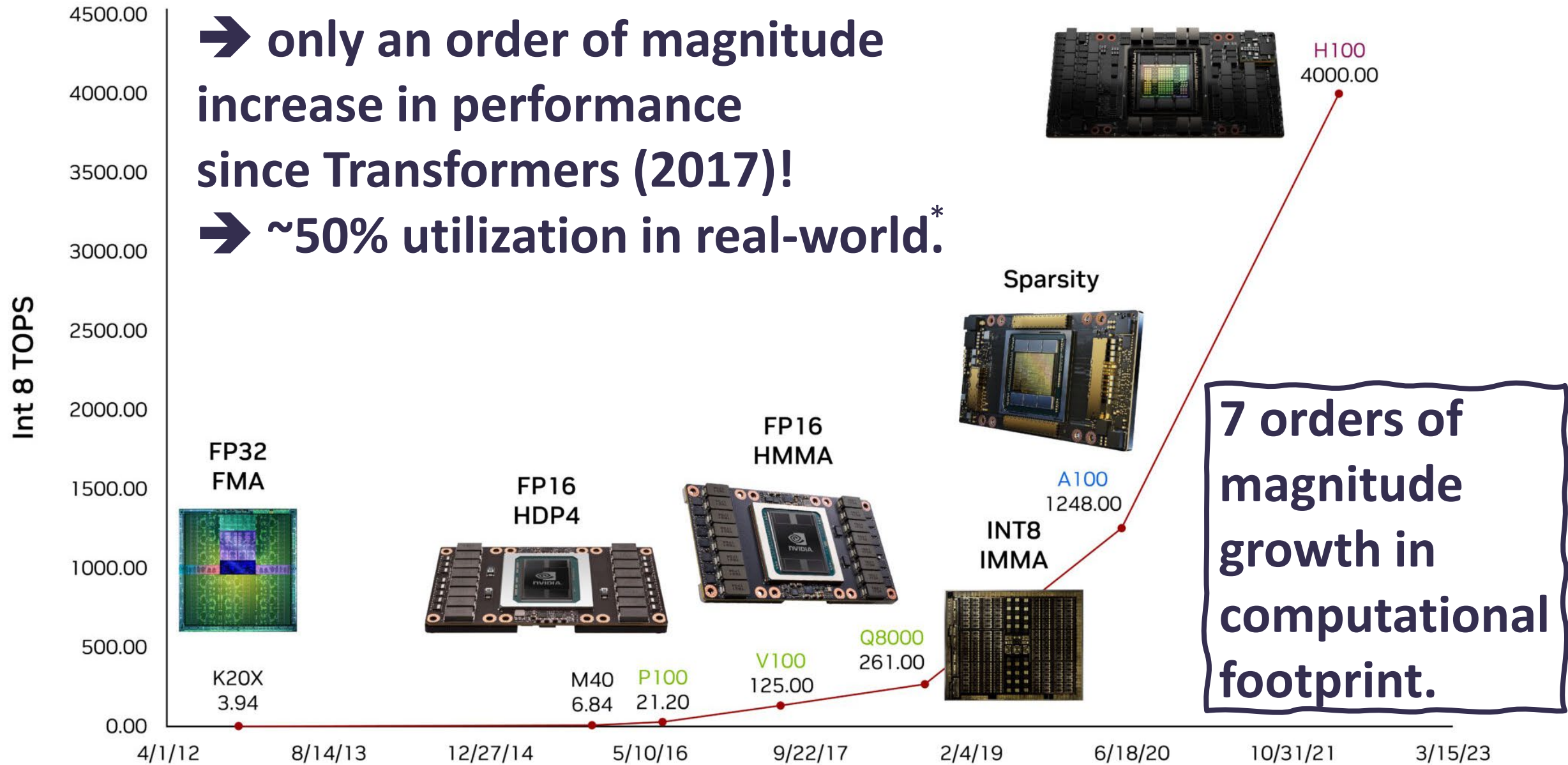


- tend to be more efficient
- but less accessible

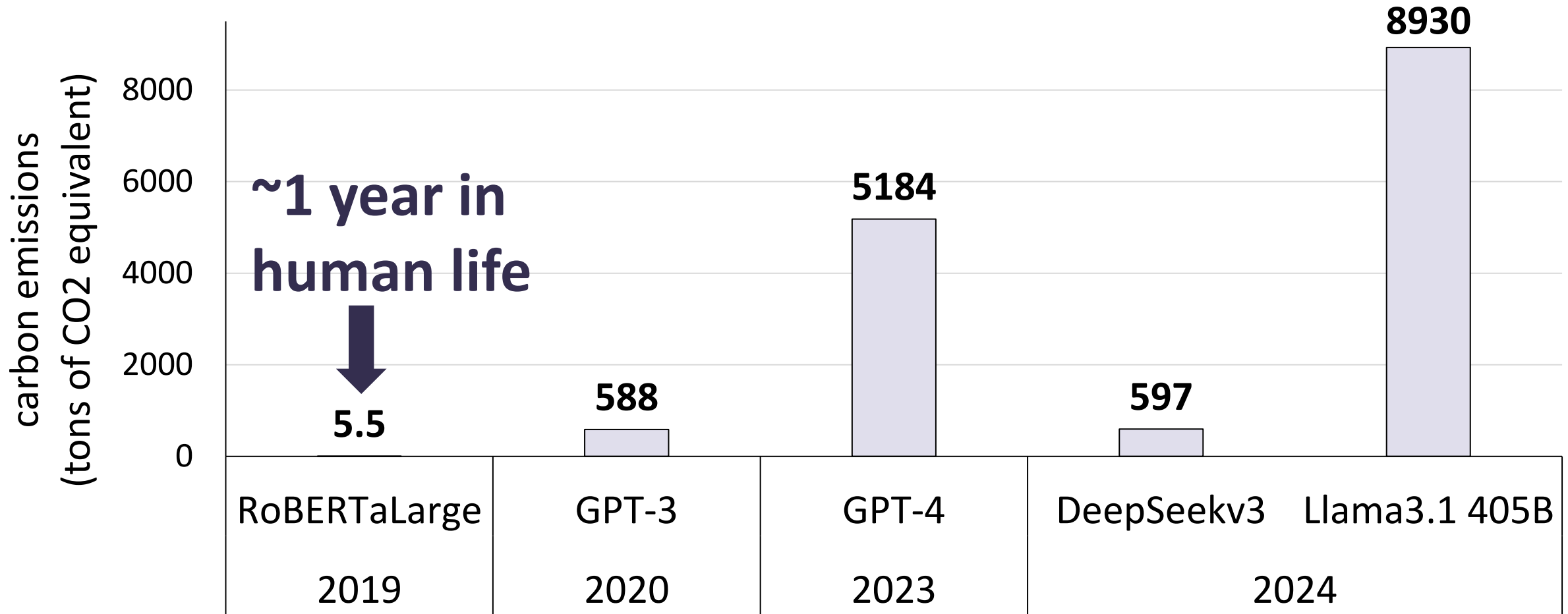


costs & progress depend on the performance & utilization of the available hardware.

NVIDIA GPUs (2012 – 2023)

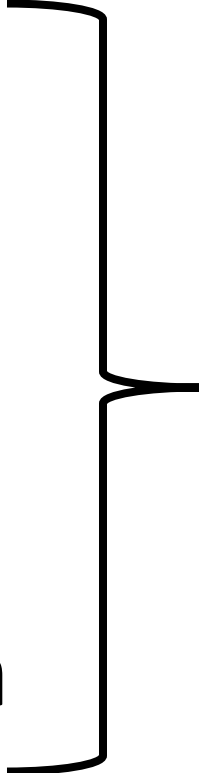


carbon footprint of language model training

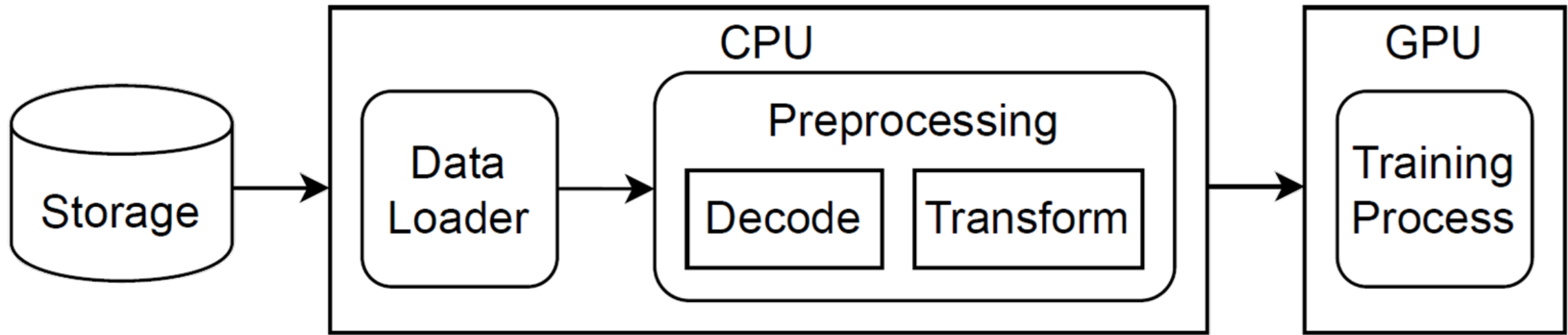


can we do better while using fewer resources?
model accuracy cannot be the only metric to aim for!

deep learning with fewer resources

- GPU-centric data path
 - data & work sharing
 - impact of data selection
- 
- for model training

journey of data in deep learning training



CPU feeds the GPU

- 16-64 CPU cores per GPU (recommended)
- 96 CPU cores per TPU*

➔ otherwise, GPU/TPU may be underutilized

➔ can we do more with fewer CPUs & less of the CPU?

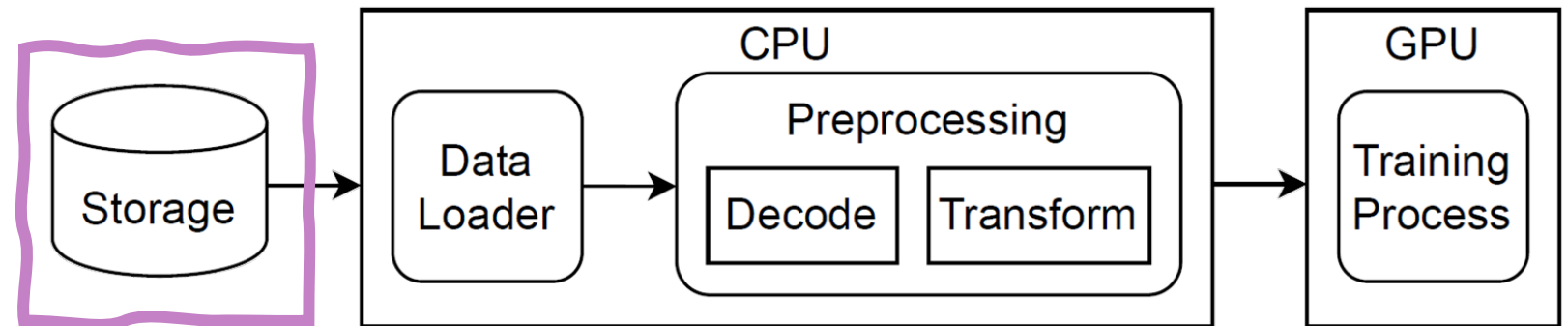
deep learning with fewer resources

[Path to GPU-Initiated I/O for Data-Intensive Systems](#)

Karl B. Torp, Simon Lund, Pinar Tözün.

DaMoN 2025

- GPU-centric data path
- data & work sharing
- impact of data selection



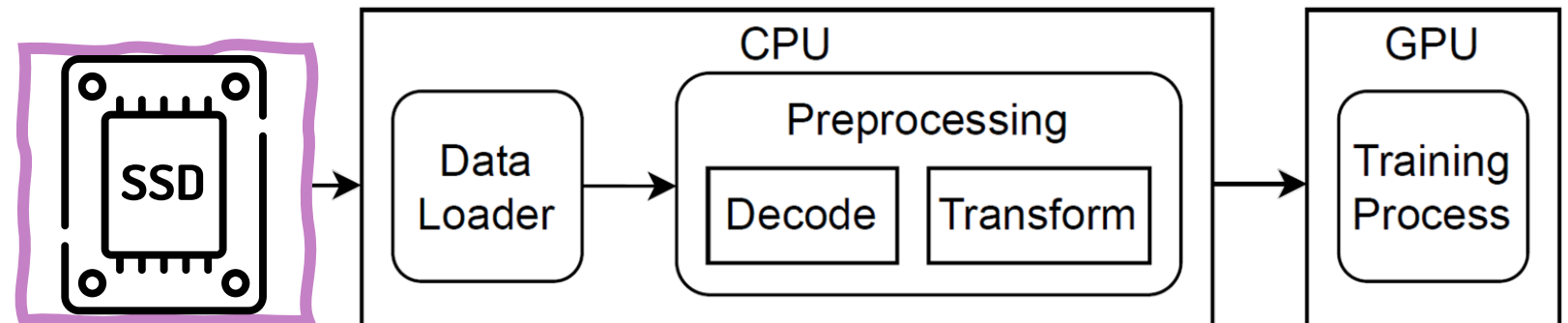
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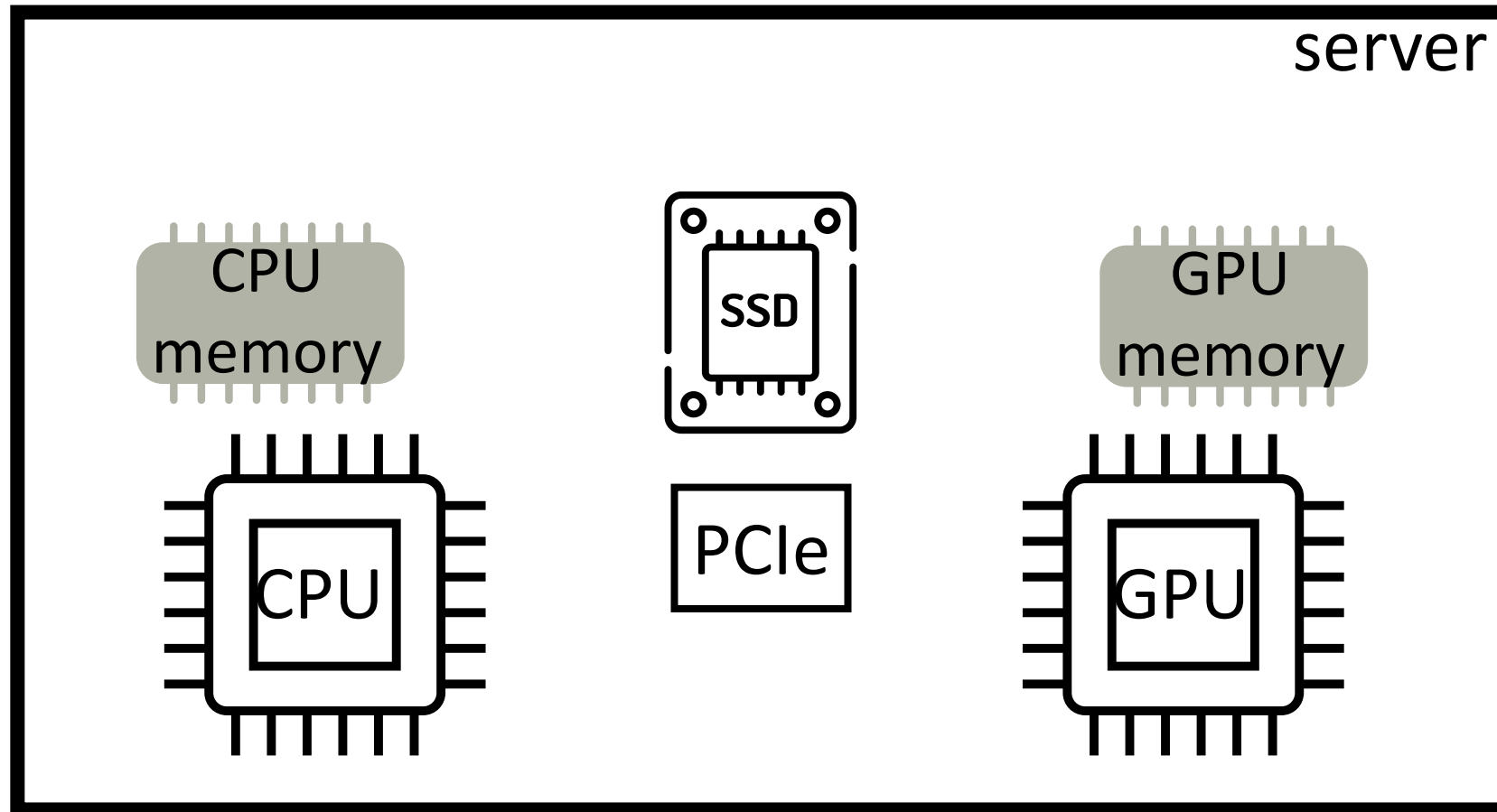
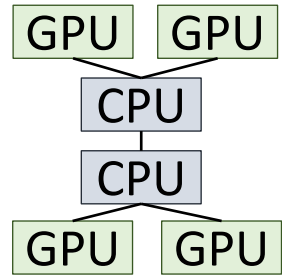
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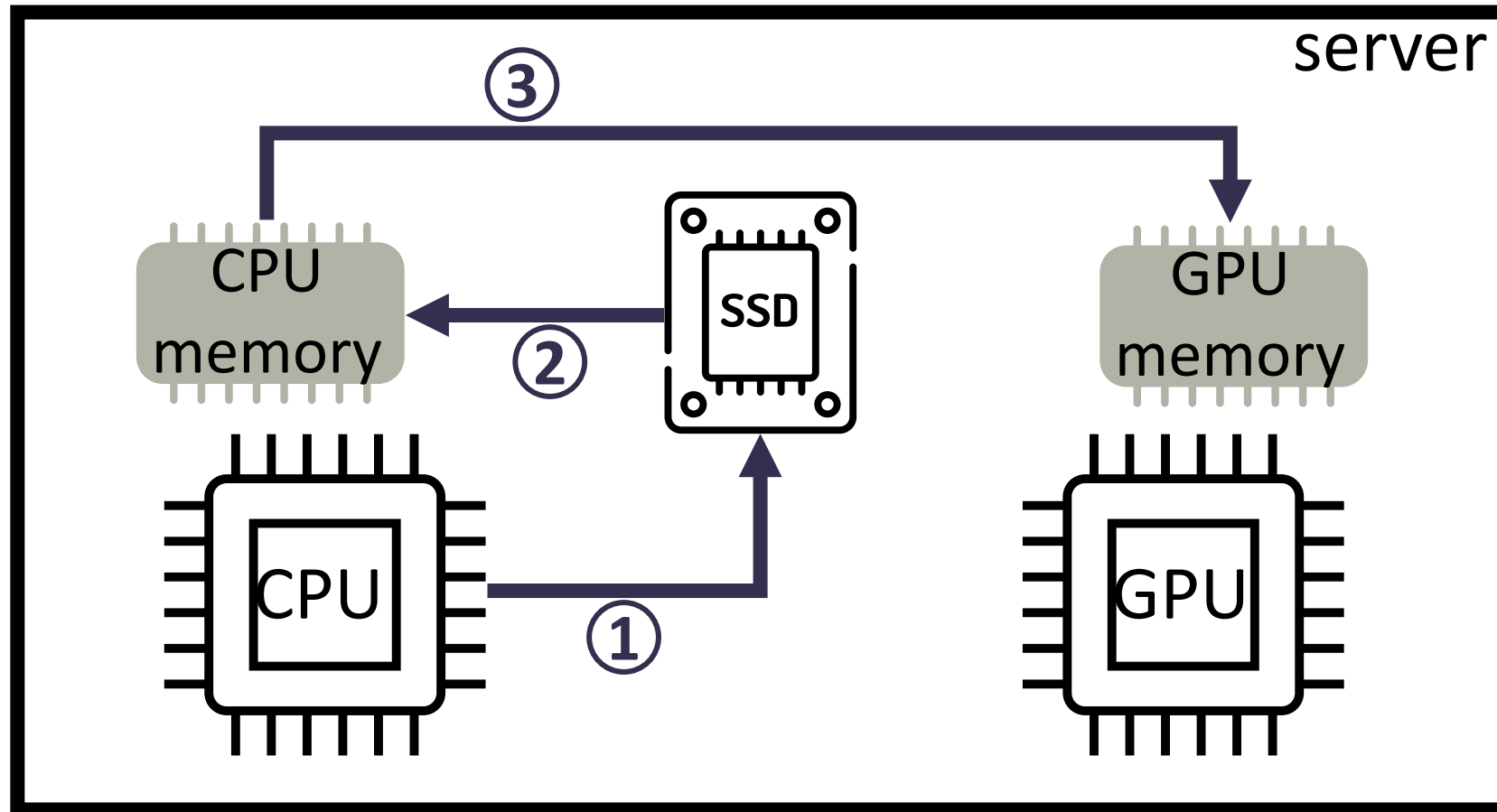


target hardware setup



* PCIe is dropped in the remaining figures for the sake of simplicity in illustrations.

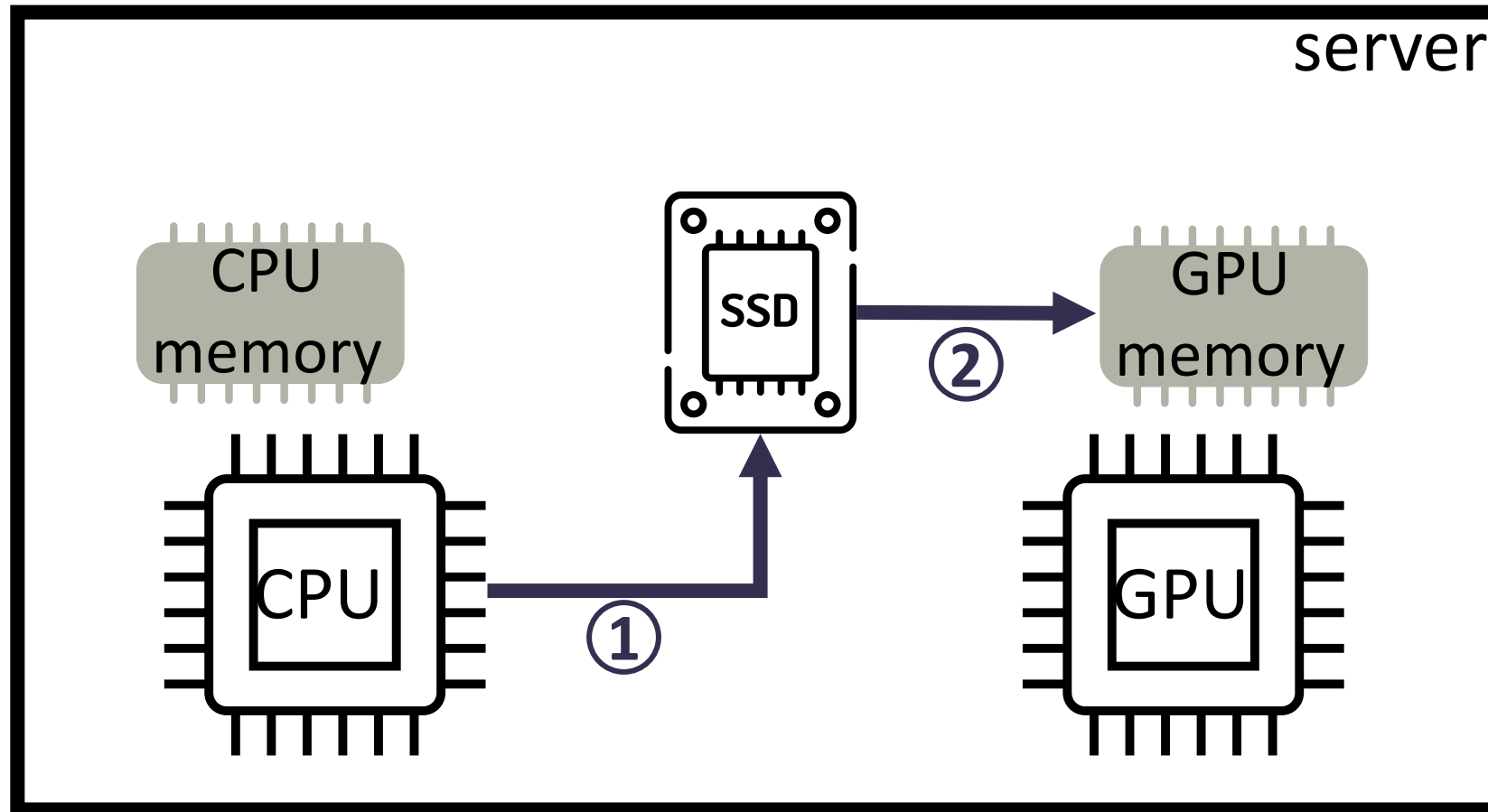
conventional: CPU-centric



- ✓ ecosystem support
- × CPU-bound & overhead from memory copy

GDS: GPU-centric & CPU-initiated

GPU Direct
Storage
[NVIDIA'19]



- ✓ eliminates the extra memory copy
- × still CPU-bound

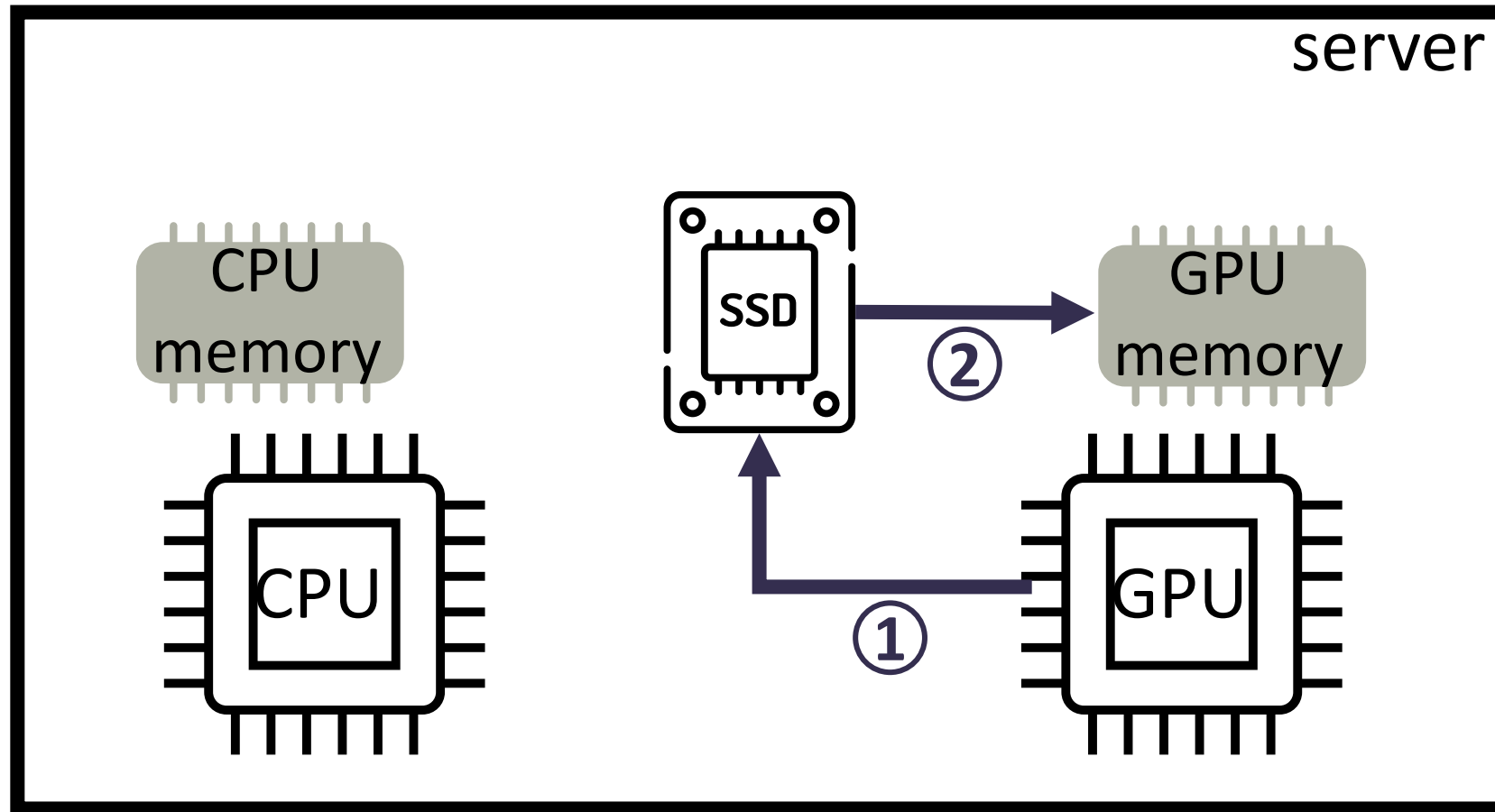
BaM: GPU-centric & GPU-initiated

Big

Accelerator

Memory

[ASPLOS'23]



- ✓ eliminates the CPU on the path
- × ecosystem missing & saturates GPU

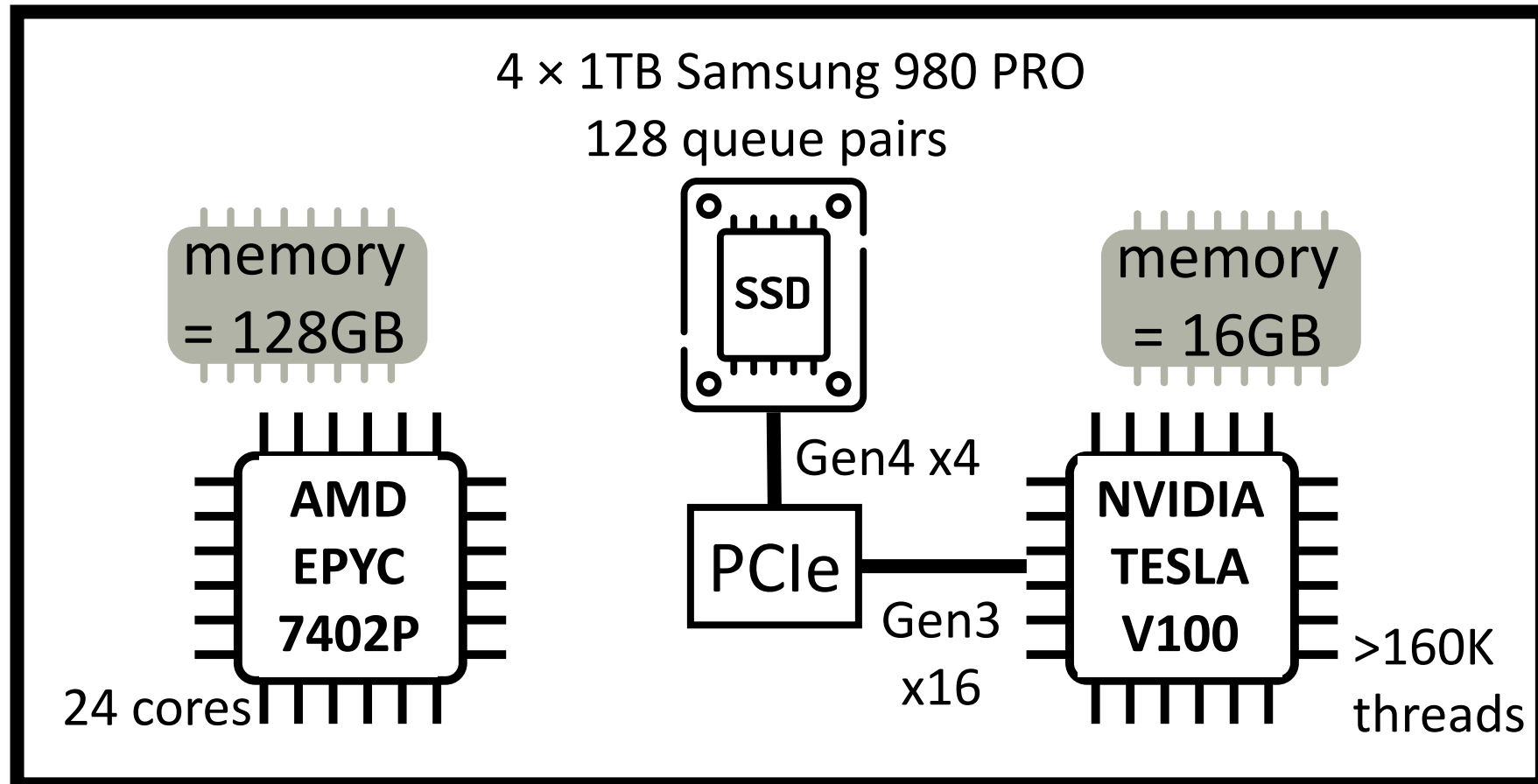
CPU- vs GPU-centric storage access

mechanisms: CPU-centric: SPDK & GPU-centric: GDS, BaM

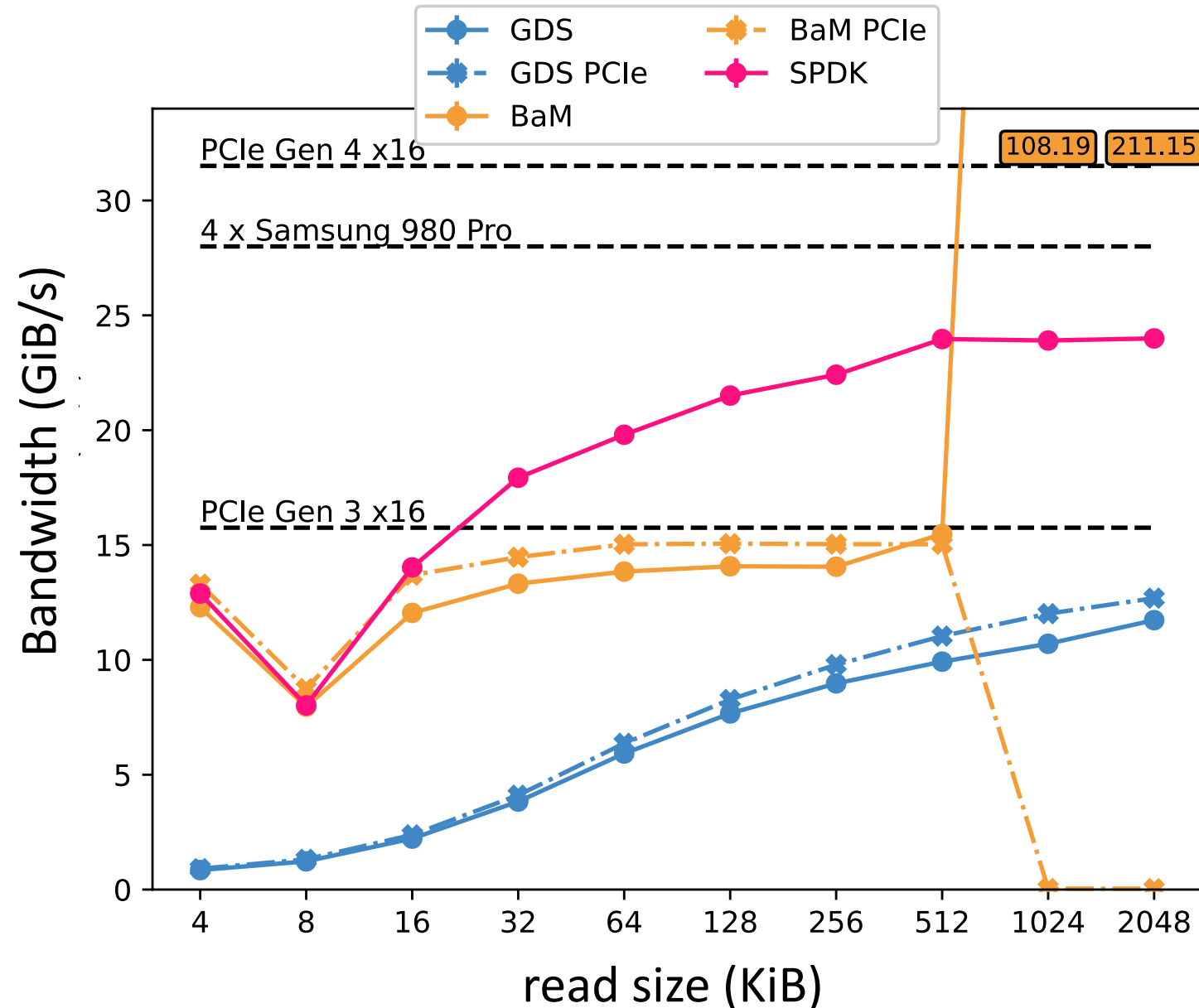
workload: random reads

→ each mechanism has their own tool for benchmarking

hardware



bandwidth utilization – 4 SSDs & PCIe



GDS is CPU-compute heavy.

➔ 16 logical cores utilized

BaM is limited by the PCIe Gen3 link & heavy on the GPU resources.

➔ whole GPU utilized

CPU-centric SPDK is resource-efficient but has a longer path to the GPU.

➔ 2 logical cores utilized

path to GPU-centric storage access

- need to reduce the dependency on CPUs for more efficient deep learning pipelines
- GPU-centric data path is a way to do that & we have the mechanisms today (e.g., GDS, BaM)
 - GDS has dependency on CPUs still
 - BaM requires a lot of GPU resources

→ when to use which mechanism while being resource-aware?

→ how to best integrate them into popular deep learning frameworks (or GPU databases) for wider-scale use?

deep learning with fewer resources

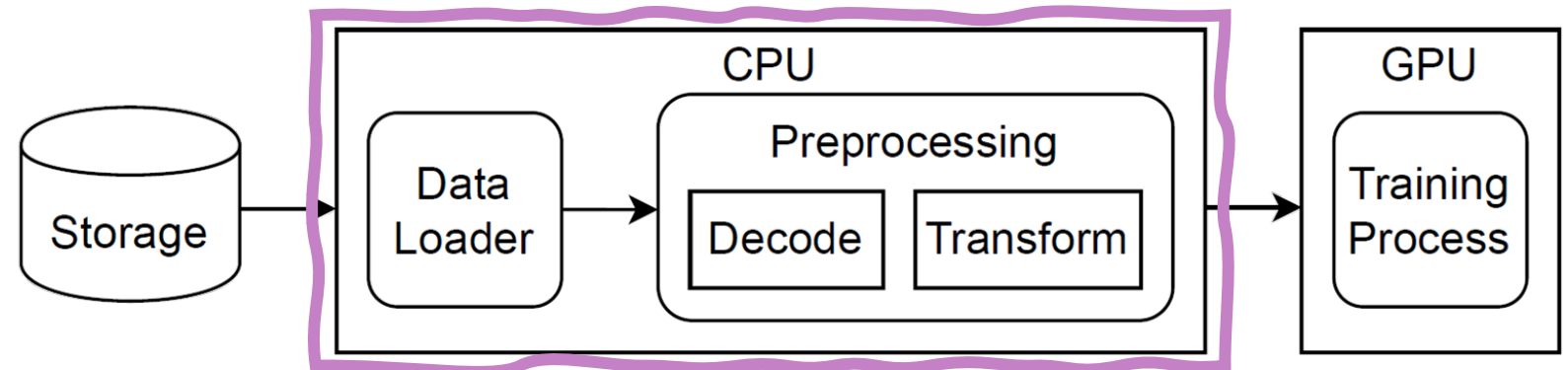
- GPU-centric data path

- data & work sharing

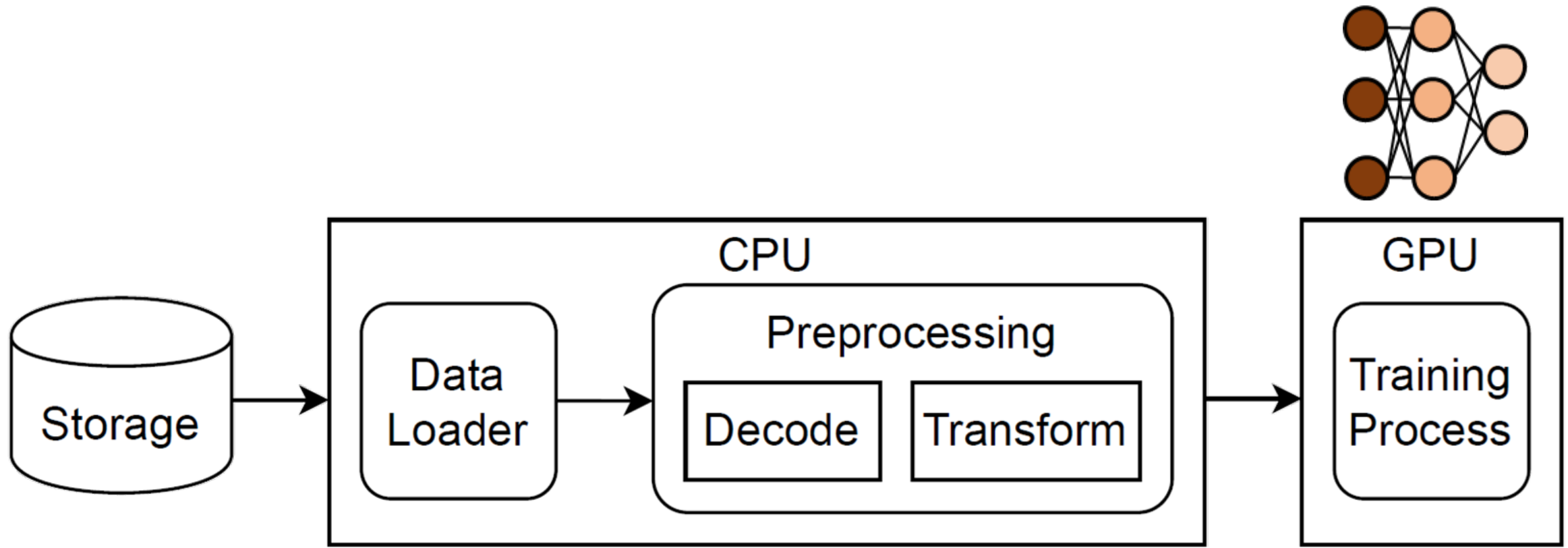
[TensorSocket: Shared Data Loading for Deep Learning Training](#)

Ties Robroek, Neil Kim Nielsen, Pinar Tözün.
SIGMOD 2026

- impact of data selection



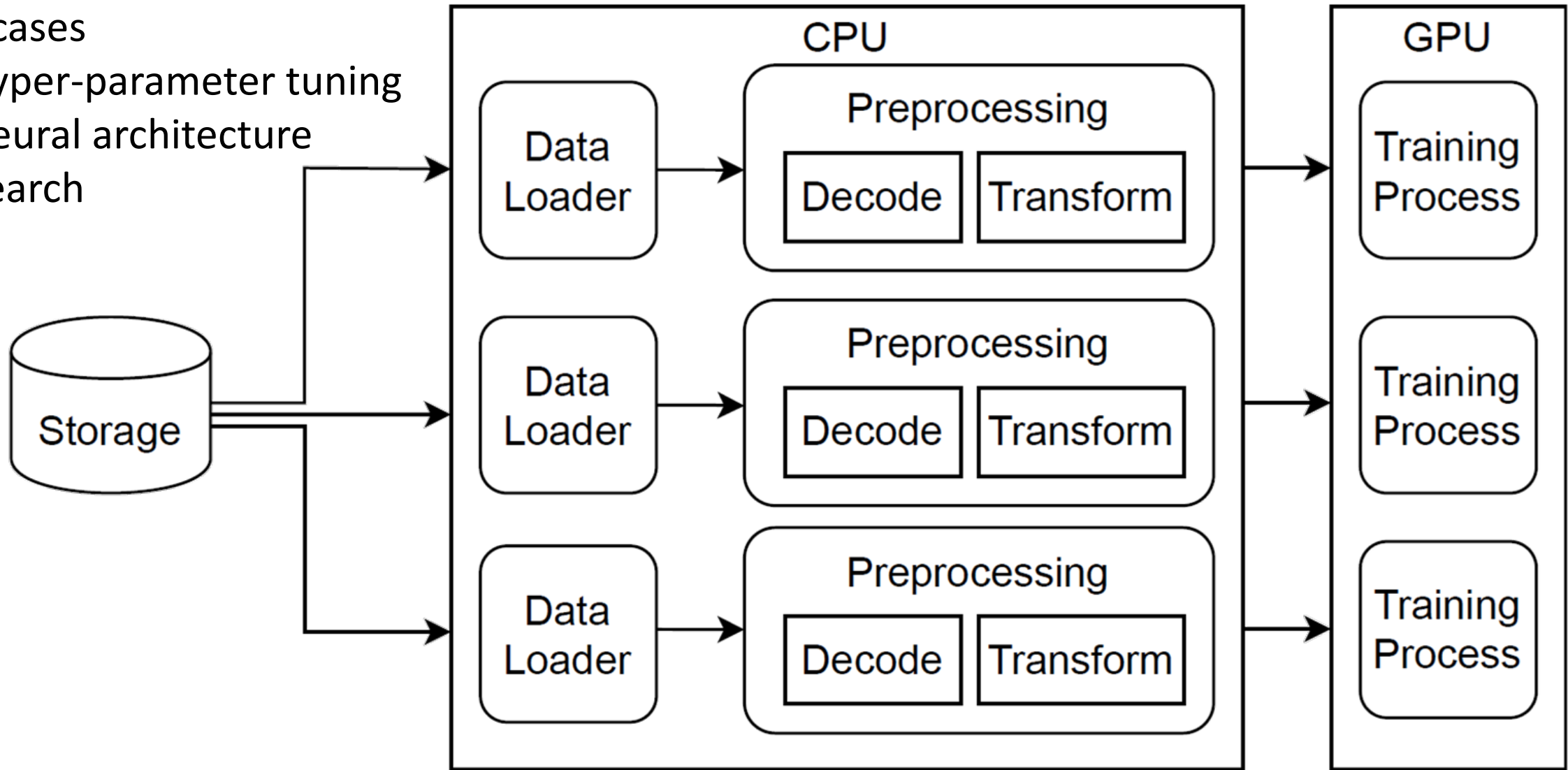
conventional journey of data while training



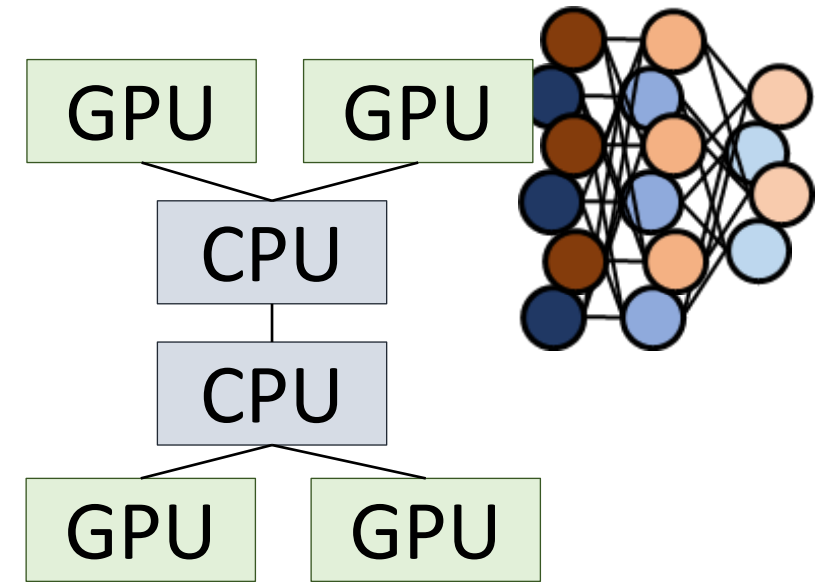
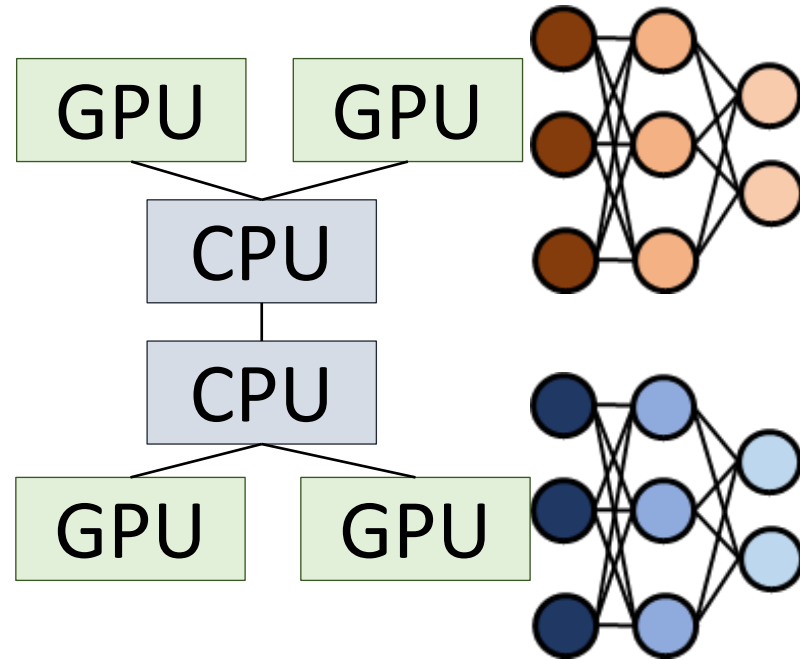
multiple model training on the same data

use cases

- hyper-parameter tuning
- neural architecture search
- ...

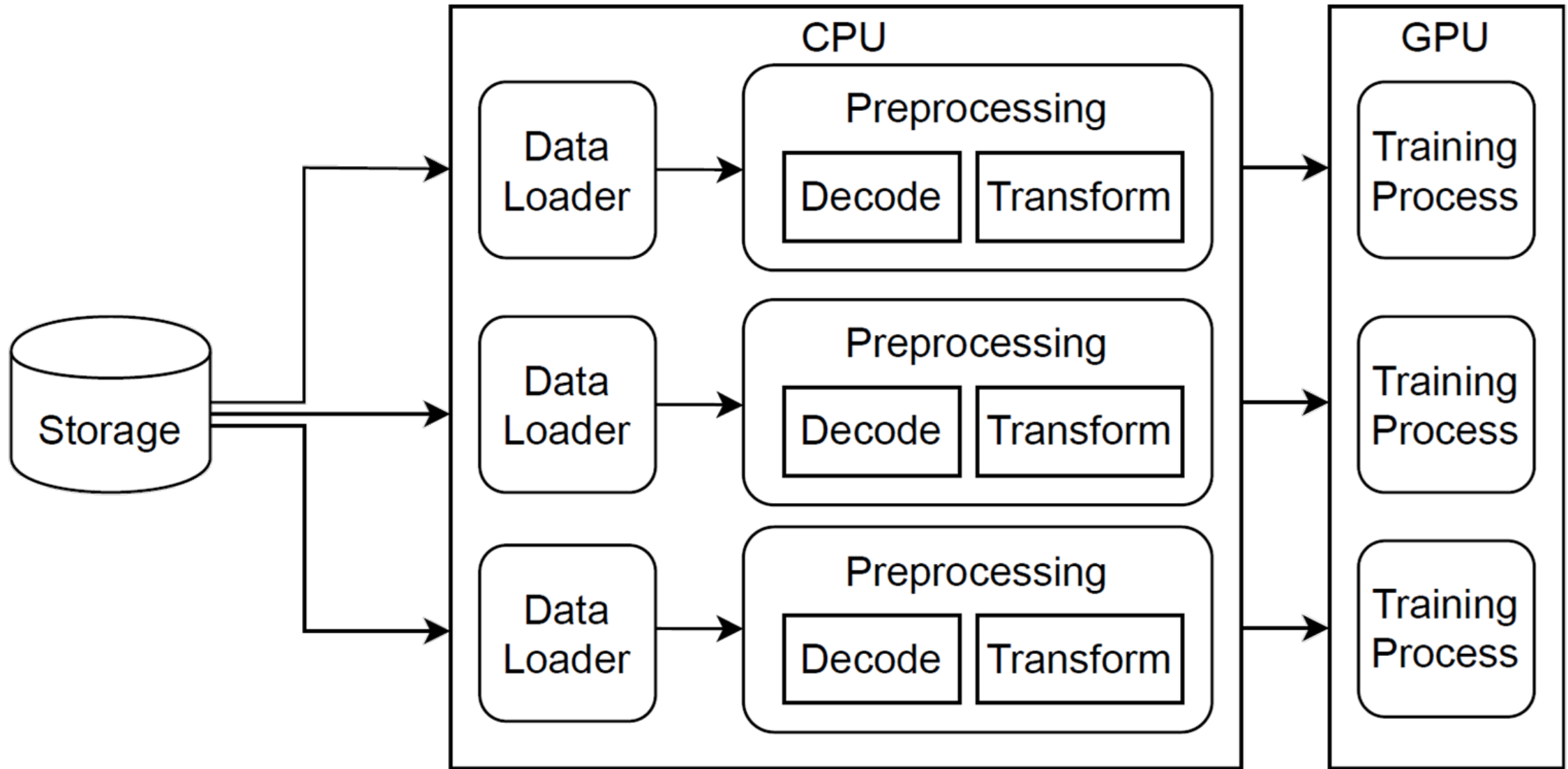


collocated training



- ➔ training more models with fewer hardware resources
- ➔ leads to better hardware utilization & reduces costs

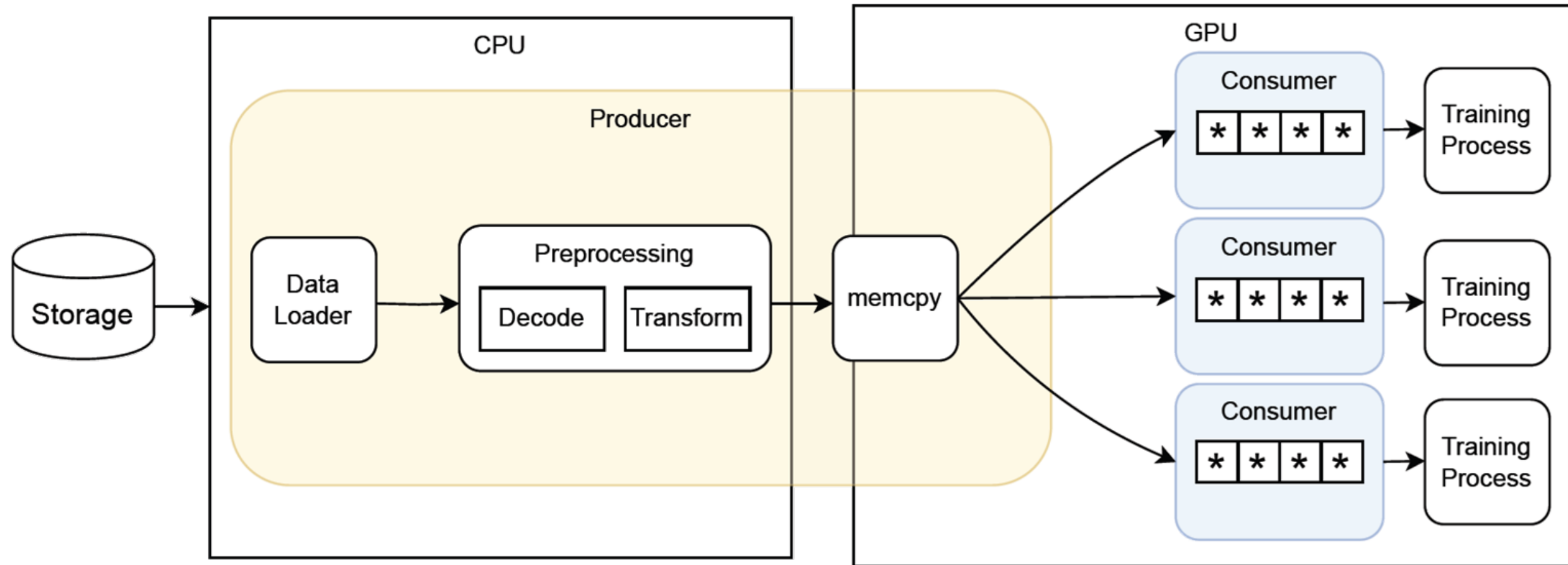
multiple model training on the same data



redundant work & CPU use!

data sharing for colocated training

TensorSocket



minimize the redundancy!

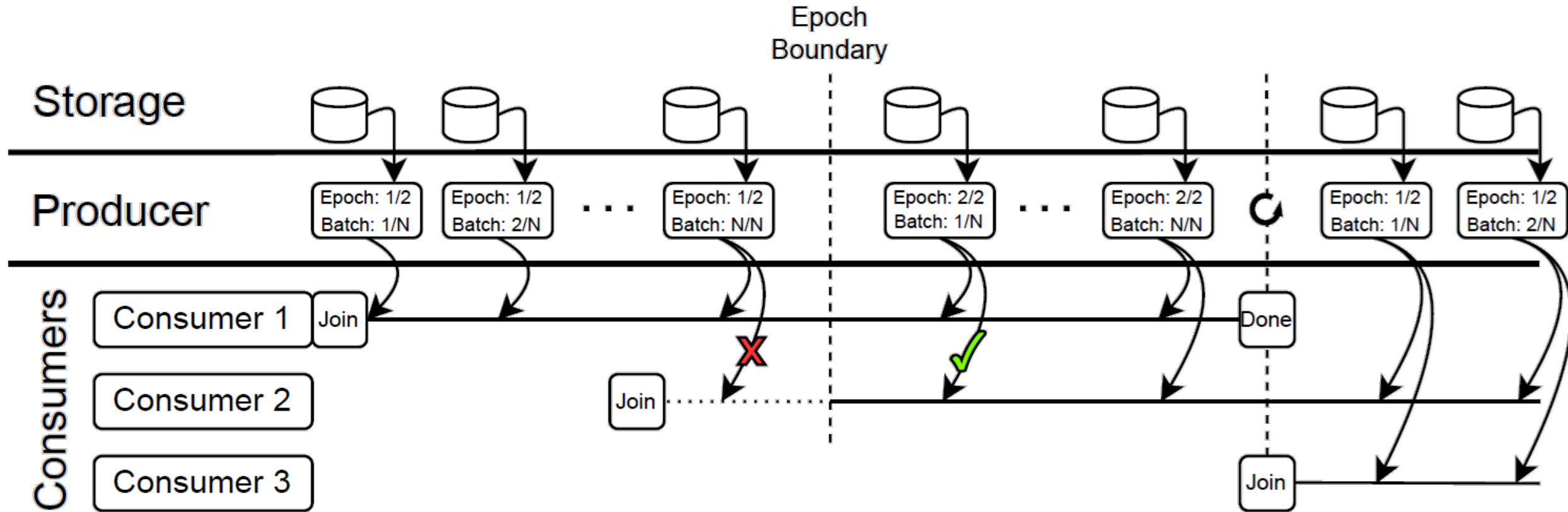
TensorSocket requirements & limitations

➔ consumers go through the *same dataset* at the *same rate*

but consumers can ...

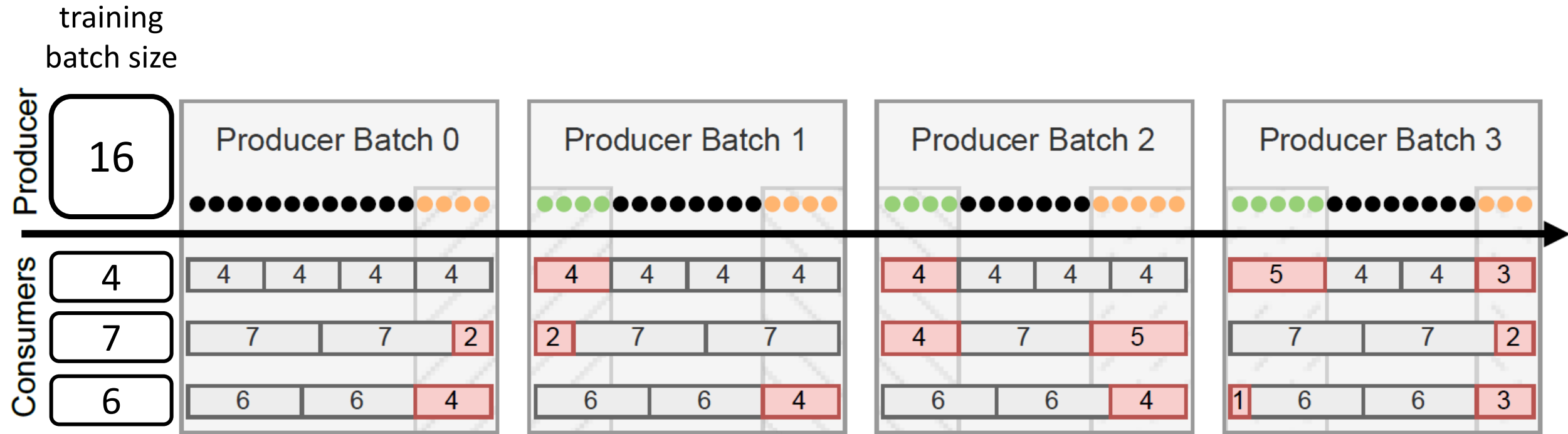
- join at different epochs of training
- have different batch sizes
- be different models

consumers joining at different epochs



trade-off of training latency for throughput & resources.
training is trial-&-error → latency is less critical.

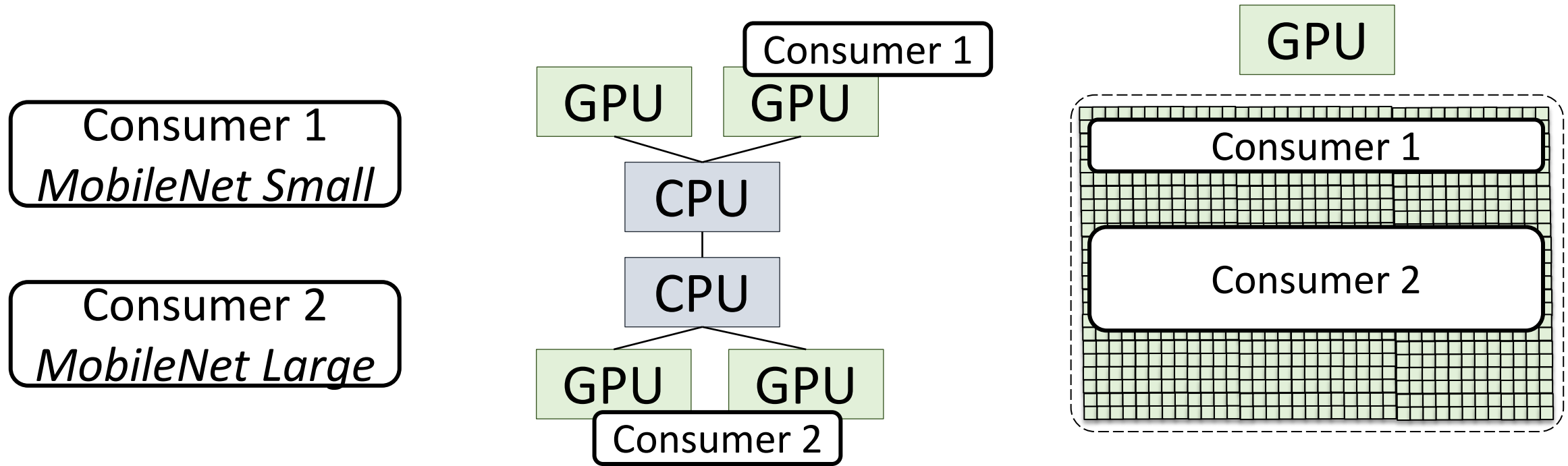
flexible batch sizing



trade-off of repeated data to get flexibility.

in practice, batch sizes tend to be multiples of 2.

different consumers / models



can adjust the hardware resources per consumer to ensure each goes over the data at the same rate

TensorSocket requirements & limitations

➔ consumers go through the *same dataset* at the *same rate*

but consumers can ...

- join at different epochs of training
- have different batch sizes
- be different models

➔ **target is smaller scale**

- collocation of model training on a single server
- models fit into the memory of a single GPU

not everyone needs “big” models & scale!

for larger scales, check out *tf.data service*, *CoorDL* ...

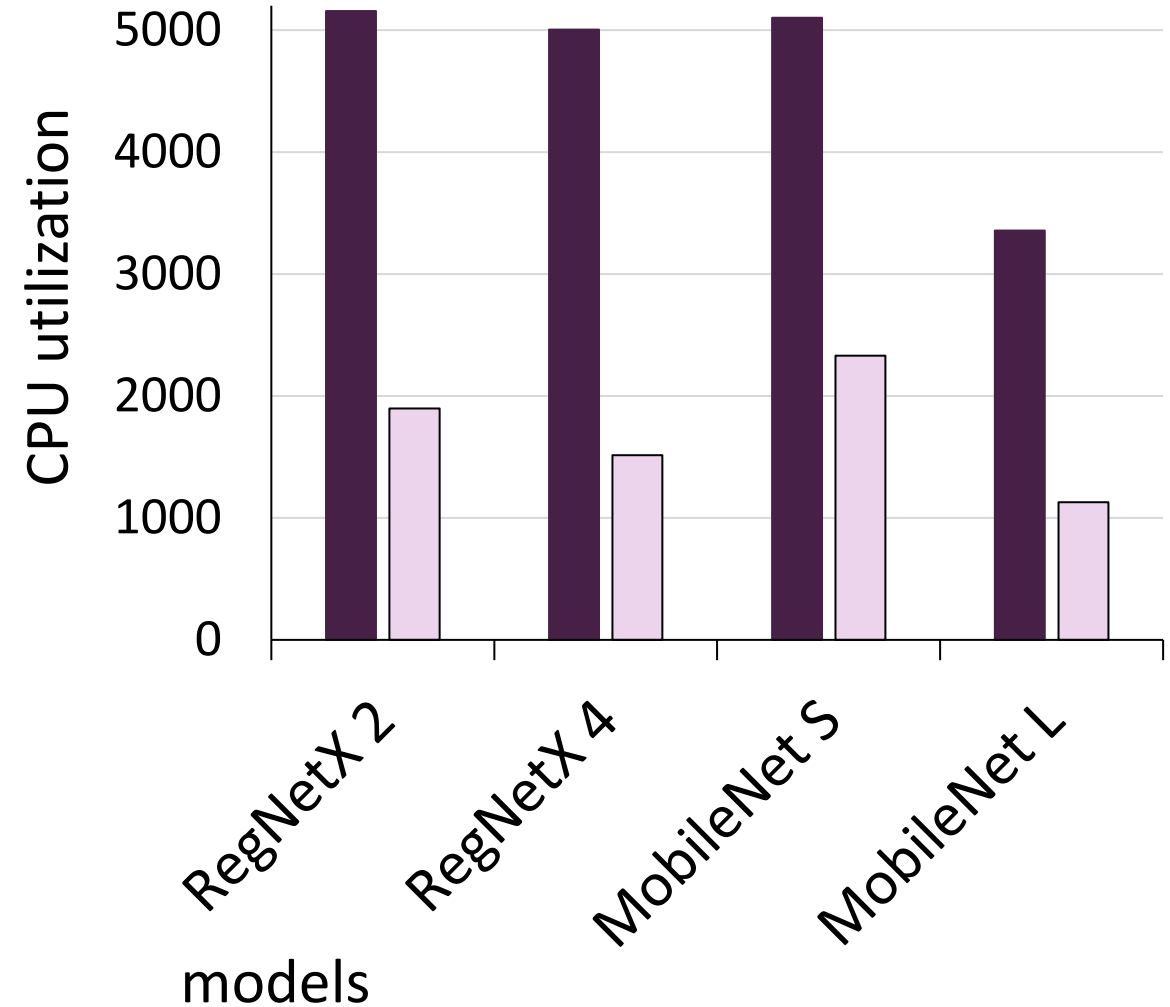
- Varoquaux et al. [Hype, Sustainability, and the Price of the Bigger-is-Better Paradigm in AI](#)
- Margot Seltzer, SIGMOD'25 keynote

[\[SoCC'23\]](#)

[\[PVLDB'21\]](#)

impact of data sharing

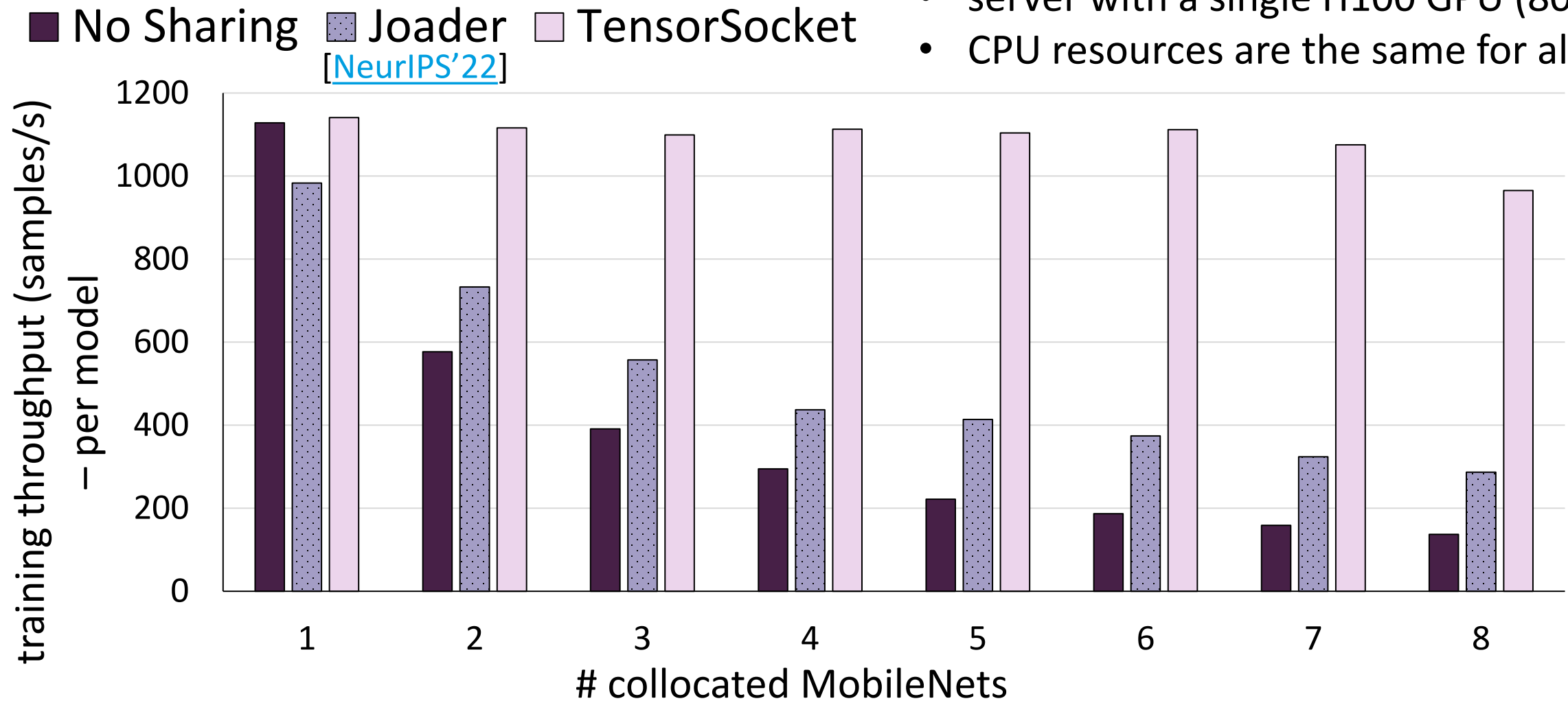
- on PyTorch
- a server with 4 A100 (40GB) GPUs
- one model training on each



higher overall throughput & reduced CPU need!

comparison to other techniques

- server with a single H100 GPU (80GB)
- CPU resources are the same for all

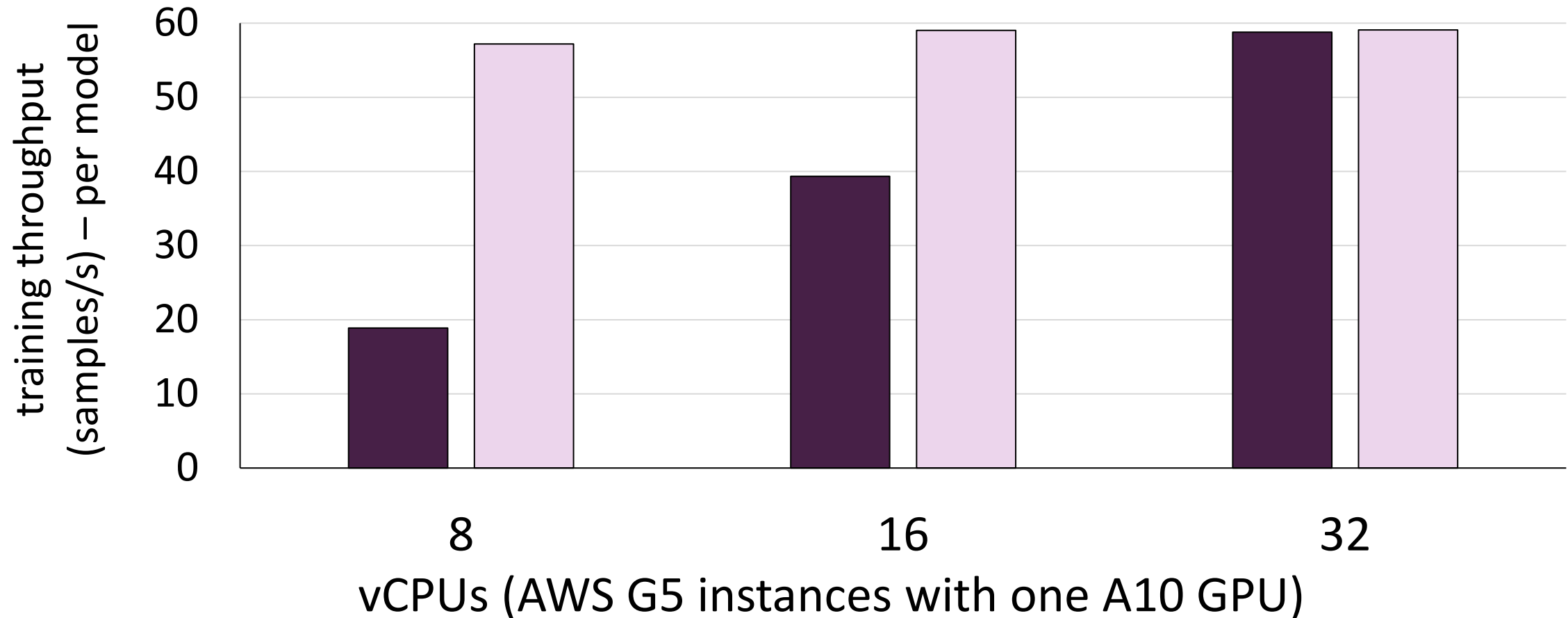


TensorSocket sustains throughput even with GPU collocation & reduces both CPU and GPU needs for the whole workload.

cloud cost savings

■ No Sharing ■ TensorSocket

- CLMR (audio classification model training)
- 4-way collocation



75% less vCPU need for the same training throughput
➔ 50% cost savings on AWS

sharing for deep learning training

- workload collocation allows data & work sharing
- ***TensorSocket*** enables data & work sharing for collocated training jobs on the same dataset.



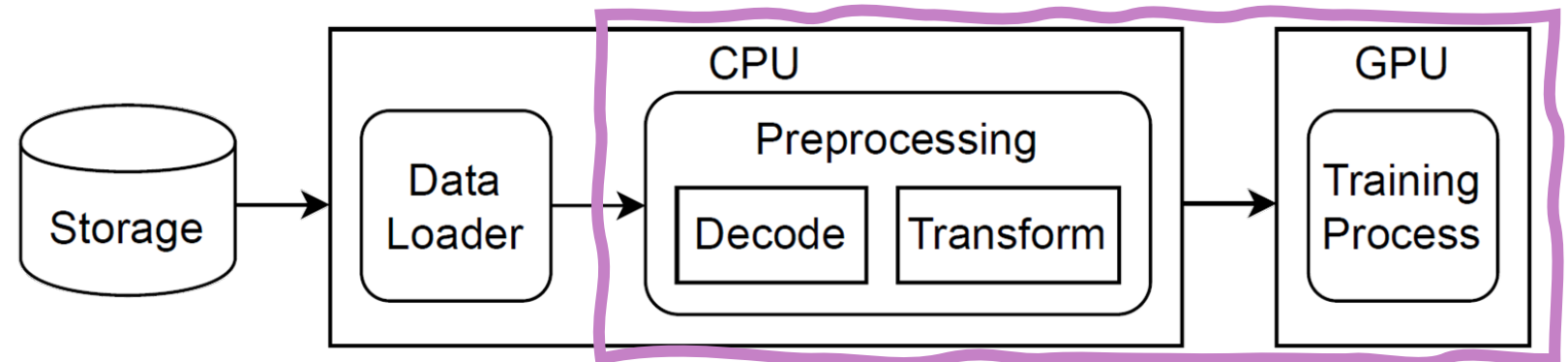
reduces both the CPU & GPU needs (& costs) of training while increasing training throughput!

deep learning with fewer resources

- GPU-centric data path
- data & work sharing
- impact of data selection

Collaboration started at 2024 Dagstuhl seminar:
[Resource-Efficient Machine Learning](#).

T. Robroek, M. Böther, **N. Christiansen**, **D. Sepehri**, D. Kainmüller, T. Rekatsinas, S. Scherzinger, A. Klimovic, P. Tözün.



why data selection?

- reduce the dataset size
- increase model accuracy
- fine-tuning

➔ **unclear impact on the end-to-end training time!**

➔ **trade-off: computational complexity
vs “better” data selection**

preliminary results

base model = Llama-3.2-1B-Instruct
dataset = TruthfulQA

server with a single H100 GPU (80GB)

	duration (mins)	GPU energy use (Wh)	accuracy gain over base model
LESS (25%) [ICML'24]	318	1099	80%
Full	84	417	84%
Random (50%)	43	215	63%
Random (25%)	23	118	39%

if the data selection can be used across different fine-tuning processes, the costs may amortize.

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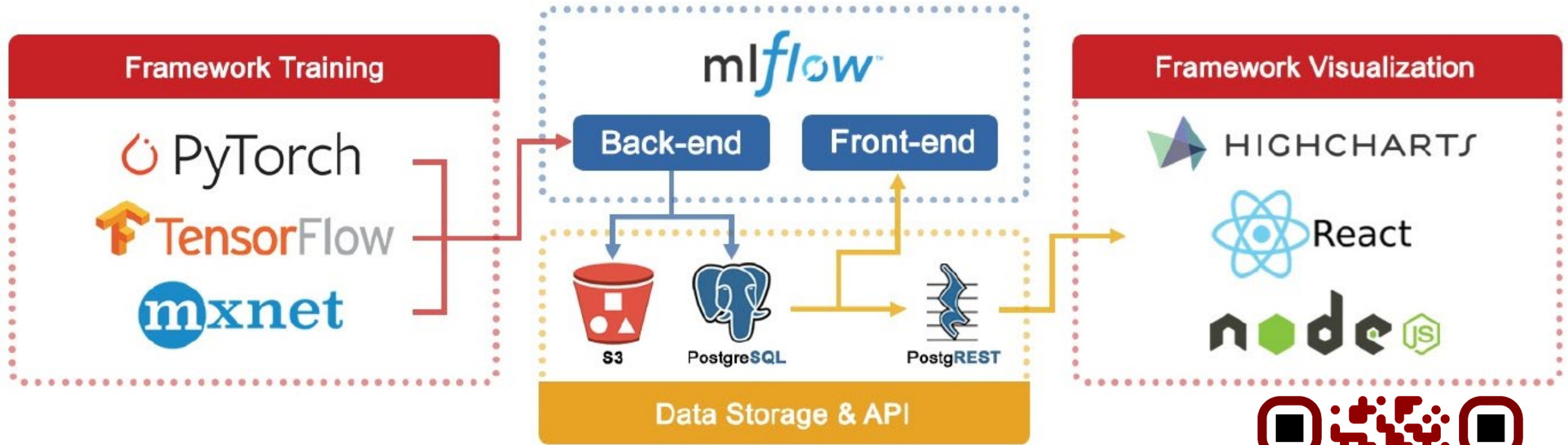
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how to monitor hardware? – radT



- easy, extensible, and scalable tracking of hardware metrics (GPU utilization, storage access, carbon footprint ...)
- frontend for data exploration



used by our group & data scientists @ITU for systematic benchmarking of deep learning training

RAD - resource-aware data systems

postdocs



Ties
Robroek



Ehsan
Yousefzadeh-
Asl-Miandoab

phd students



Robert
Bayer



Jens Birk
Andersen

collaborators



Pamela Delgado
HES-SO



Tilmann Rabl
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Ana Klimovic
ETH



Julian Priest
ITU



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thank you!